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   [IF=1.310]

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2012


2011


2010


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     [IF=5.210]


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     [IF=1.364]

**2008**


**2007**


2006


2005

2004

2003

Before 2003
\[IF=2.348\]


\[IF=2.727\]

\[IF=2.727\]

Book Chapters


\[A\]


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2. T. N. Do*, T. Tjahjowidodo, M. W. S. Lau, **S. J. Phee**, Adaptive Control of Position Compensation for Cable-Conduit Mechanisms Used In Flexible Surgical Robots, the 11th


2013


2012


2011


2010


2009


2008


2007


2006


2005


2004


2003

Before 2003
International Patents/Granted and Pending

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<th>No.</th>
<th>Title</th>
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<th>Application/Grant No.</th>
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<td>1</td>
<td>Robotic Endoscope and an Autonomous Pipe Robot for Performing Endoscopic Procedures</td>
<td>USA</td>
<td>U.S. Patent 6,162,171</td>
<td>Dec 2000</td>
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<td>2</td>
<td>Intuitive Control Device for Motorized Furniture</td>
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<td>System and Method for Accurate Percutaneous Needle Placement in Soft Tissue Under Ultrasound Guidance</td>
<td>US PRV</td>
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<td>4</td>
<td>Endoscopic Device for Locomotion through the Gastro-intestinal Tract</td>
<td>USA</td>
<td>U.S. Patent 6,939,291</td>
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<td>7</td>
<td>Surgical Robotic System for Flexible Endoscopy</td>
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<td>61/182,556 2010/138083</td>
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<td>Robotic System for Flexible Endoscopy</td>
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<td>Flexible Endoscopy System and Methods Providing a Selectively Shape Lockable Endoscope Probe, a Combined Independently Operable</td>
<td>US PRV</td>
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<td>Primary/Secondary Endoscope Probe Structure, and Quick Connect/Disconnect Interfaces that Link an Actuation Controller and Disposable Actuation Assemblies through which Tendon-Sheath Based Arms are Driven</td>
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